

Constraint Programming

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General Concepts

- Constraint Programming is a paradigm for solving combinatorial problems.
- Other approaches:
 - Mixed Integer Programming
 - Evolutionary algorithms
 - Search algorithms in a state space (e.g., blind search, heuristic search such as A^*).
 - Simulated annealing
 - Taboo algorithm
 - ...

General Concepts

- A combinatorial problem is a problem ...
 - ... which can be modelled as entities ...
 - ... maintaining relations ...
 - ... and in which a solution must be found:
the solution to the problem.
- There can be several solutions.
 - Finding one
 - Finding the best one

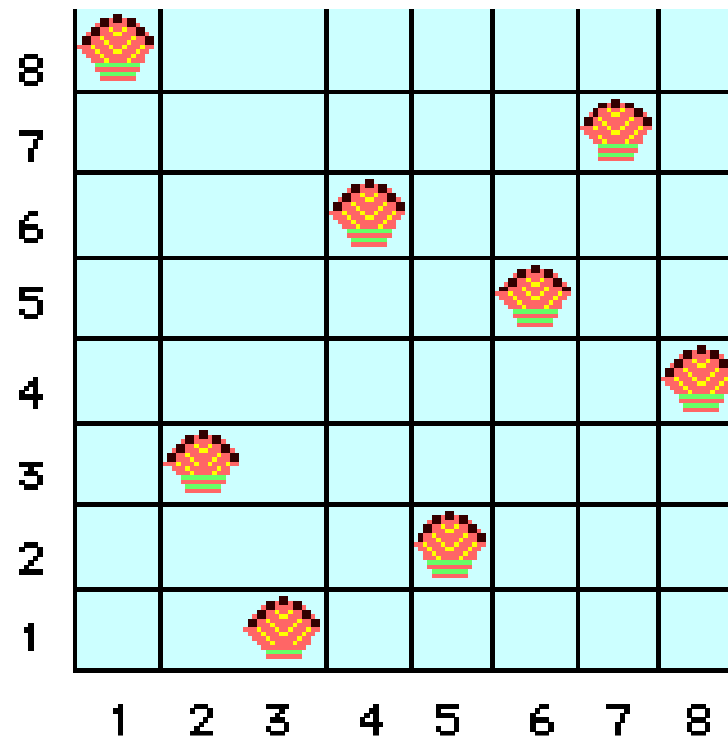
General Concepts

- Example of a combinatorial problem: the sudoku game.

		7	8				1	9
8							7	5
4					9			
			5		2	7		
		2	3			1		
5	6			1		3		4
2					6			1
	8	3		2		9	4	7
		5	4	9		8	6	

General Concepts

- Example of a combinatorial problem: the N-queen problem (here, $N = 8$).



General Concepts

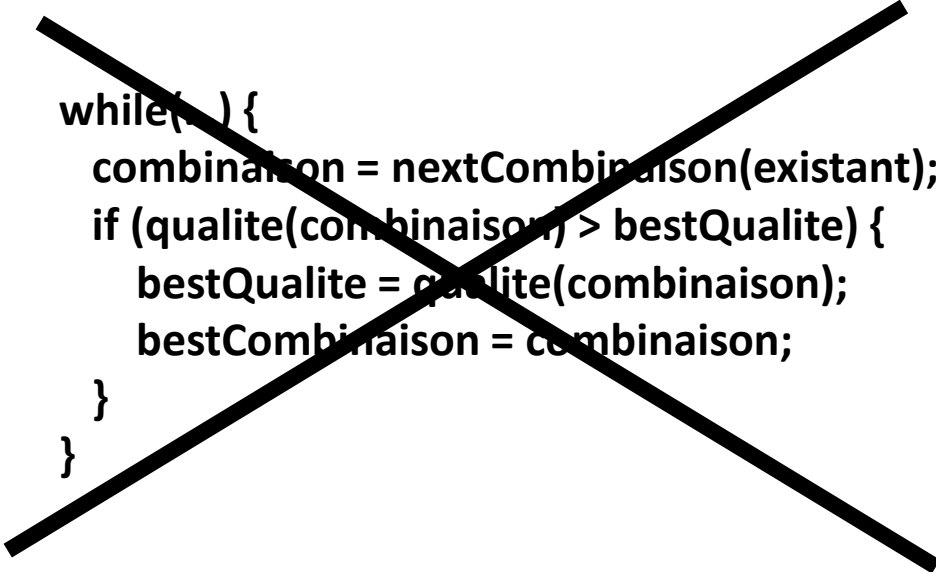
- Example of combinatorial problem: cryptarithmetics.

$$\begin{array}{r} \text{SEND} \\ + \text{MORE} \\ \hline \text{MONEY} \end{array}$$
$$\begin{array}{r} \text{UN} \\ \text{DEUX} \\ + \text{DEUX} \\ + \text{DEUX} \\ + \text{DEUX} \\ \hline \text{NEUF} \end{array}$$

General Concepts

- The difficulty: the number of combinations to consider can be gigantic for a real world problem.
 - Example: for the sudoku game, a coarse estimation of the number of combinations is :
 $(8!)^9 \approx 10^{41}$ combinations.
 - For small combinatorial problems, (almost) every algorithm should work ...
- Consequence : browsing all these combinations one by one would take a gigantic time, even on the fastest computer.
 - Phenomenon of combinatorial explosion.
 - In the worst case, the number of combinations to consider is an exponential function of the size of one dimension of the data.

General Concepts



```
while(1) {  
    combinaison = nextCombinaison(existant);  
    if (qualite(combinaison) > bestQualite) {  
        bestQualite = qualite(combinaison);  
        bestCombinaison = combinaison;  
    }  
}
```

MUCH TOO LONG !!!!
(except on small problems)

General Concepts

- Idea of constraint programming:
 - Consider the structure of the problem:
Decompose the problem as
 - Variables
 - Each variable has a finite domain (variable expressed in extension).
 - Relations among variables (constraints)
 - A constraint must always be satisfied; It reduces the variables' domains.
 - A unique algorithm cleverly uses this model.
 - Heuristics

General Concepts

- Other example of split between model and solver:
 - Fact base / rule base and inference engine in knowledge-based systems.
 - (Mixed Integer) Linear Programming in Operational Research.
- Consequence:
 - A user writes a model and gives heuristics.
 - The Constraint Programming engine searches for a solution.

General Concepts

- Examples of problems « solvable » by CP:
 - Assign companies to interns while following their wishes.
 - Optimally plan air traffic (assign flight corridors to aircrafts, optimize flight crew shifts, ...)
 - Schedule tasks, so that the makespan is minimized and the resources consumption minimized.
 - Optimize component location on a mother board.
 - Build a menu both healthy and tasty in a restaurant.
 - ...

General Concepts

- Constraint Programming has been proposed by Jean-Louis Laurière in 1976 in his HdR.
- Seminal Publication:
 - Jean-Louis Laurière, A Language and a Program for Stating and Solving Combinatorial Problems. [Artif. Intell. 10](#)(1): 29-127 (1978).
- Packages : CPLEX CP Optimizer from IBM, CHOCO from EMN, CHIP from COSYTEC, SICSTUS PROLOG, MINIZINC+ solvers, etc.
- French Association for Constraint Programming: <http://afpc.greyc.fr/web/>

Model

- Discrete variables with finite domain:
 - For i from 1 to n , a variable V_i
 - For j from 1 to n , a domain $D_j = \{ v_1, v_2, \dots, v_{f(j)} \}$.
 - For all i , $V_i \in D_i$
- Constraints on these variables:
 - For k from 1 to m , $C_k = (X_k, R_k)$ with :
 - $X_k = \{ V_{i1}, V_{i2}, \dots, V_{ik} \}$ // The variables of C_k
 - $R_k \subset D_{i1} \times D_{i2} \times \dots \times D_{ik}$ // The possible values of these
// variables, together compatible
// with C_k

Vocabulary

- A CSP might be:
 - Under constrained: too few constraints.
 - Over constrained: too many constraints.
- Given a CSP, one can ...:
 - Search for a solution
 - Search for all solutions
 - Search for an optimal solution given some cost function
 - Prove that there is no solution.

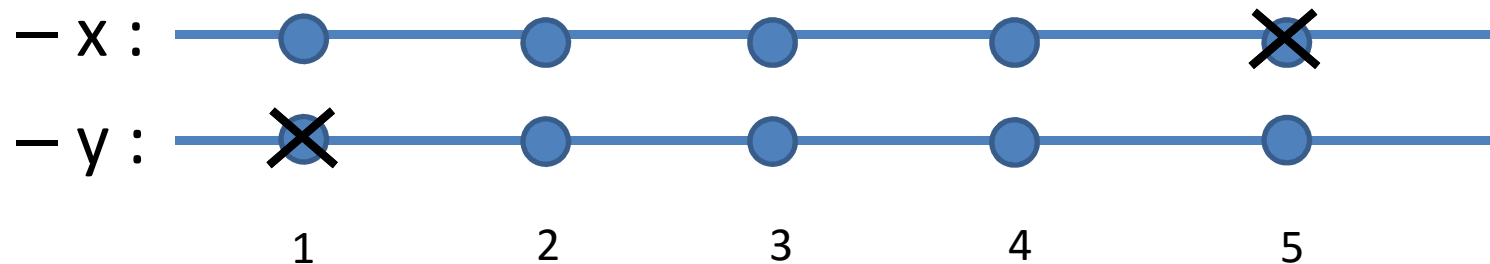
Constraints

- A constraint can be expressed:
 - In extension: give the sets of possible values of variables
 - Arithmetically: $<, \leq, >, \geq, =, \neq, +, -, /, *, \dots$
 - Logically: $\Leftrightarrow, \Rightarrow, \Leftarrow, \text{OU}, \text{ET}, \text{NON}, \dots$
 - Globally: $\text{AllDifferent}(x_1, x_2, \dots, x_n), \text{Geost}(f_1, f_2, \dots, f_n), \dots$
- A constraint can be:
 - Hard: a constraint must always be satisfied.
 - Soft: a constraint is sometimes satisfied and sometimes violated, given a criterion
- A contrainte can be:
 - Unary. Example : $x \in [1, 5]$
 - Binairy. Example : $x < y$
 - N-ary. Example : $\text{AllDifferent}(V_1, V_2, \dots, V_n)$

Constraints

- Example of hard constraints:

– $x \in [1, 5] ; y \in [1, 5] ; x < y$



- Example of soft constraints:

– In a scheduling problem,

$Y = \#(t_i < \text{deadline}_i)$ and maximize Y

Constraints

Global constraints

- **AllDifferent(V_1, V_2, \dots, V_n)**

- The variables V_i must be all different.
- Logically equivalent to:

$$\begin{aligned} &V_1 \neq V_2 \wedge V_1 \neq V_3 \wedge \dots \wedge V_1 \neq V_n \wedge \\ &V_2 \neq V_3 \wedge \dots \wedge V_2 \neq V_n \wedge \\ &\dots \wedge \\ &V_{n-1} \neq V_n \end{aligned}$$

- Property: if there are **m** variables in AllDiff, and **n** distinct values together possible, and if **m** > **n**, then the constraint cannot be satisfied.

Example of model

- A model for the sudoku game:
 - A variable is an empty cell in the grid.
 - A domain is the set of integers from 1 to 9
 - If the cell already includes a number, it appears as a constant in the constraint.
 - Constraints:
 - The variables of a small grid are all different and different from constants.
 - The variables of a row are all different.
 - The variables of a column are all different.

Example of model

- A 1st model for the N-queen problem (here, $N = 8$) :
 - A pair of variables (x_i, y_i) per queen i . The queen i is located on column x_i and on row y_i
 - The domain of x_i is $[1, 8]$
 - The domain de y_i is $[1, 8]$
 - Constraints:
 - $x_i \neq x_j$ // Different columns
 - $y_i \neq y_j$ // Different rows
 - $x_i + y_i \neq x_j + y_j$ // Different 1st diagonal
 - $x_i - y_i \neq x_j - y_j$ // Different 2nd diagonal

Example of model

- A 2nd model for the N-queen problem (here, N = 8) :
 - The variable x_i is the row of the i -th column on which the i -th queen is located.
 - The domain of x_i is $[1, 8]$
 - Constraints:
 - The constraints on columns are satisfied by construction.
 - $x_i \neq x_j$ // Different rows
 - $x_i + i \neq x_j + j$ // Different 1st diagonals
 - $x_i - i \neq x_j - j$ // Different 2st diagonals

Example of model

- A 3rd model for the N-queen problem (here, $N = 8$) :
 - The cells of the grid are numbered from 1 to 64.
 - The variable x_i is the index of the cell in this numbering at which queen i is located.
 - Constraints:
 - $x_i / 8 \neq x_j / 8$ // Different rows
 - $x_i \% 8 \neq x_j \% 8$ // Different columns
 - Constraints on the 1^e diagonal
 - Constraints on the 2^e diagonal

Example of model

- Cryptarithmetics: SEND + MORE = MONEY
- The model:
 - Variables : $S, M \in [1, 9]$; $E, N, D, O, R, Y \in [0, 9]$
 - Constraints :
 - $D + E = Y + 10 * R1$
 - $N + R + R1 = E + 10 * R2$
 - $E + O + R2 = N + 10 * R3$
 - $S + M + R3 = O + 10 * M$
 - Secondary variables : $R1, R2, R3 \in [0, 1]$

Vocabulary

- An **assignment** is the fact of assigning a variable to a value of its domain.
 - Variable V_i is assigned to its value $v_{ij} : D_i = \{ v_{ij} \}$
- An **assignment** of variables to values is :
$$A = \{(V_{i1}, v_{i1}), (V_{i2}, v_{i2}), \dots, (V_{ik}, v_{ik})\}$$
- An assignment can be :
 - **total** : every variable has a value ($k = n$)
 - **partial** : some variables have a value, but not all ($k < n$).
- An assignment A is **consistent** iff it does not violate any constraint C_k .
- A **solution** to a CSP (Constraint Satisfaction Problem) is a total consistent assignment of variables.
- Some CSPs require to maximize an objective function f .

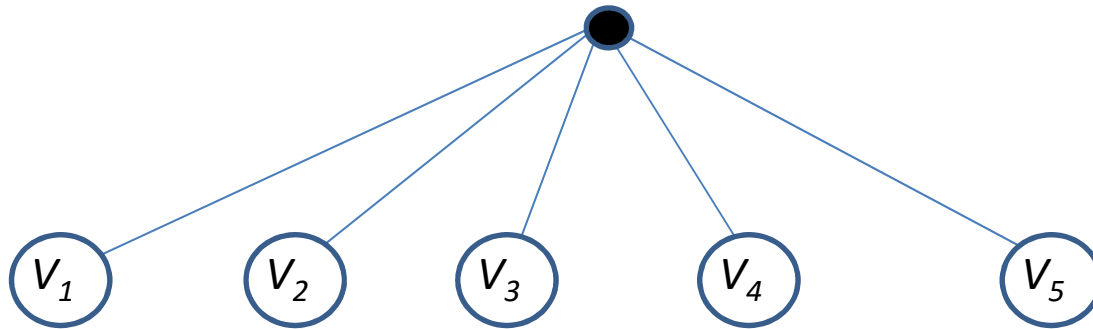
Algorithms

- Commutativity :
 - A problem is commutative iff the order of application of actions has no effect on the result.
- A CSP is commutative : when values are assigned to variables, the same partial assignment is reached whatever the order is.
- Consequence: we can assign variables one after the other, as needed.

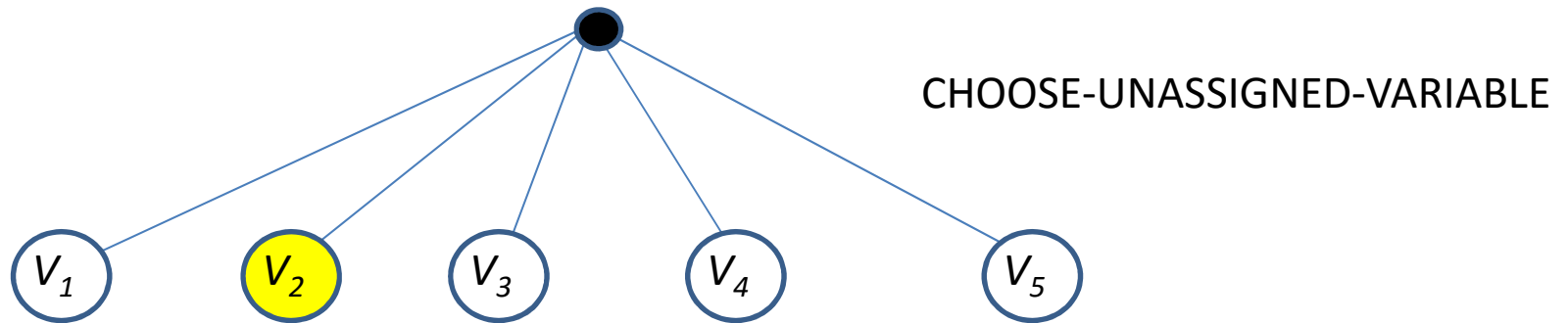
Algorithms : backtrack (1 / 14)



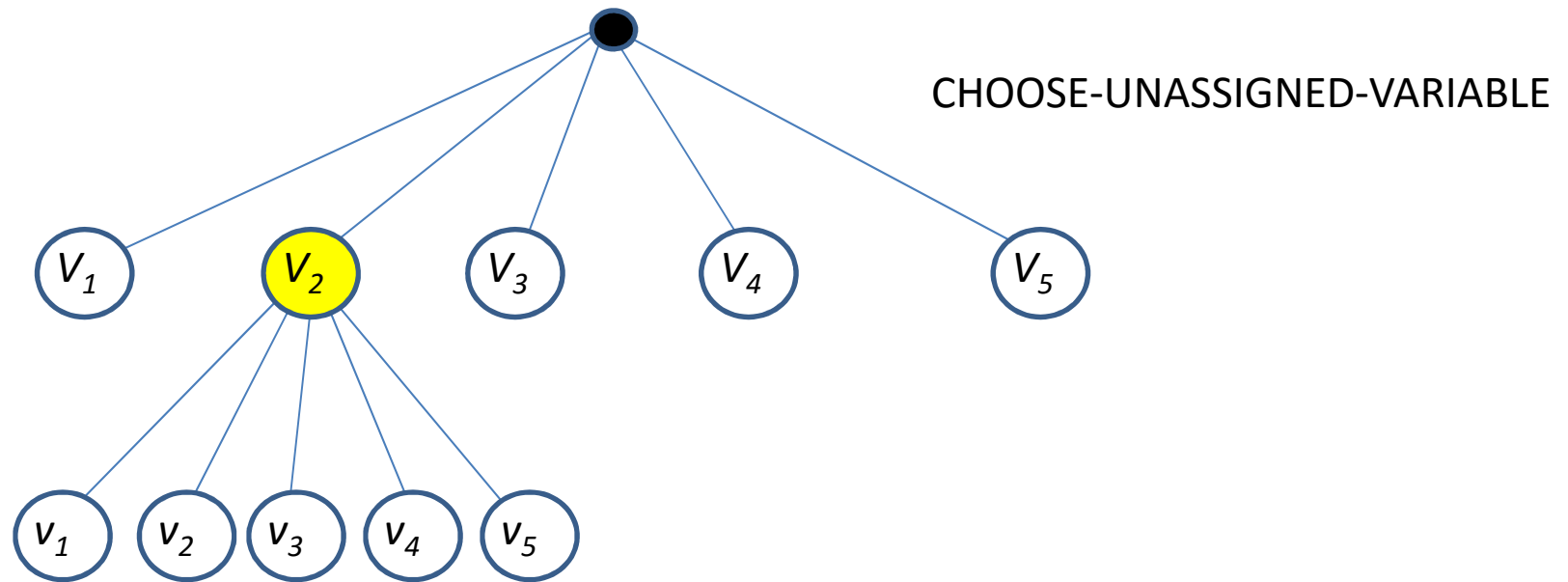
Algorithms : backtrack (2 / 14)



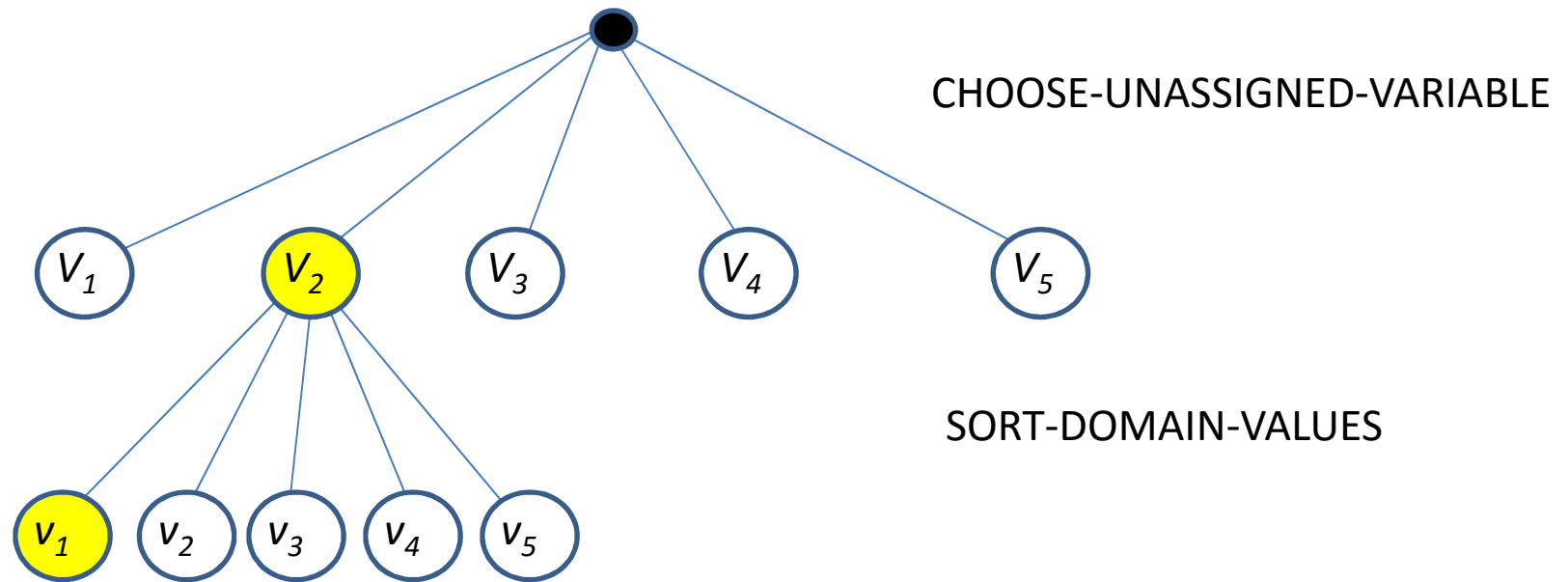
Algorithms : backtrack (3 / 14)



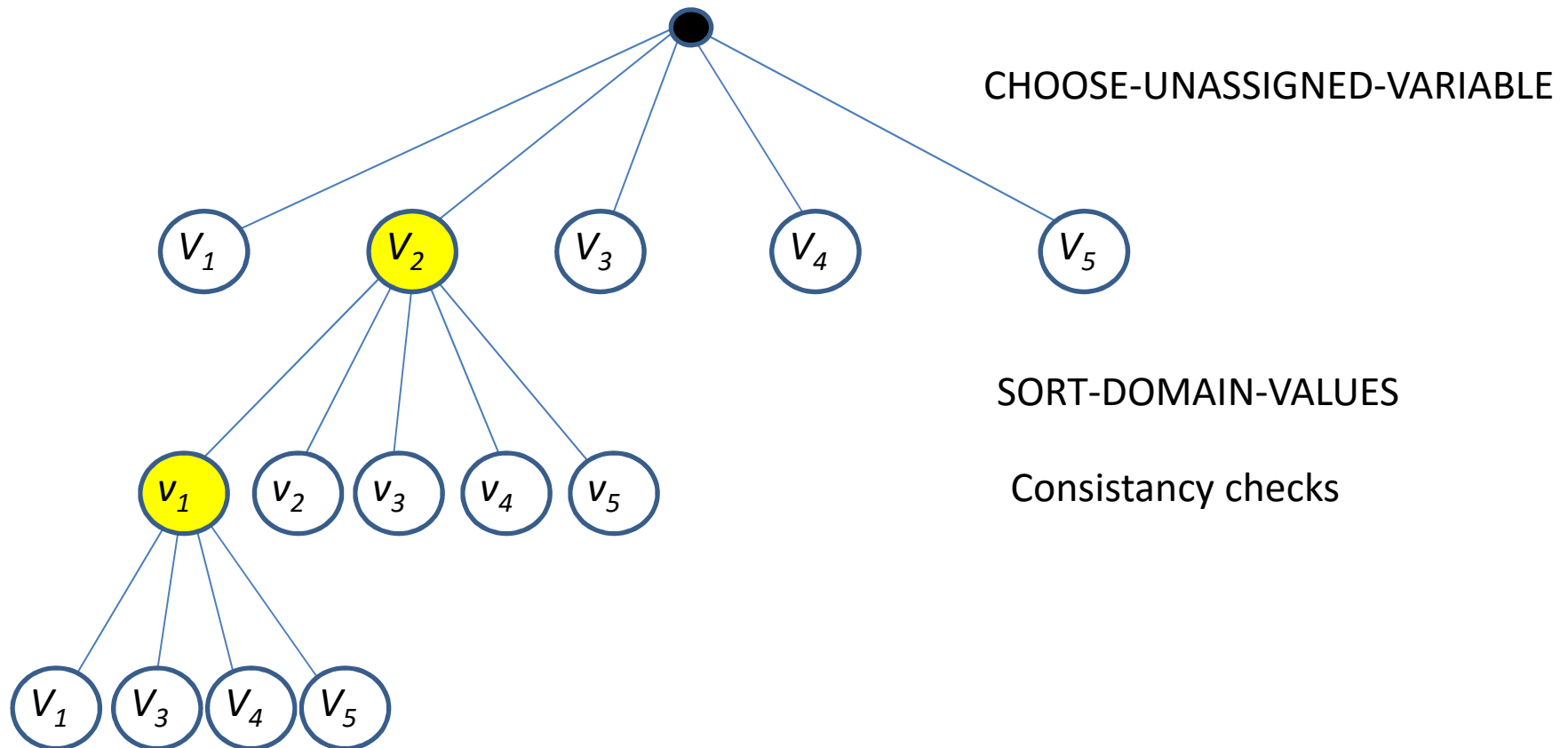
Algorithms : backtrack (4 / 14)



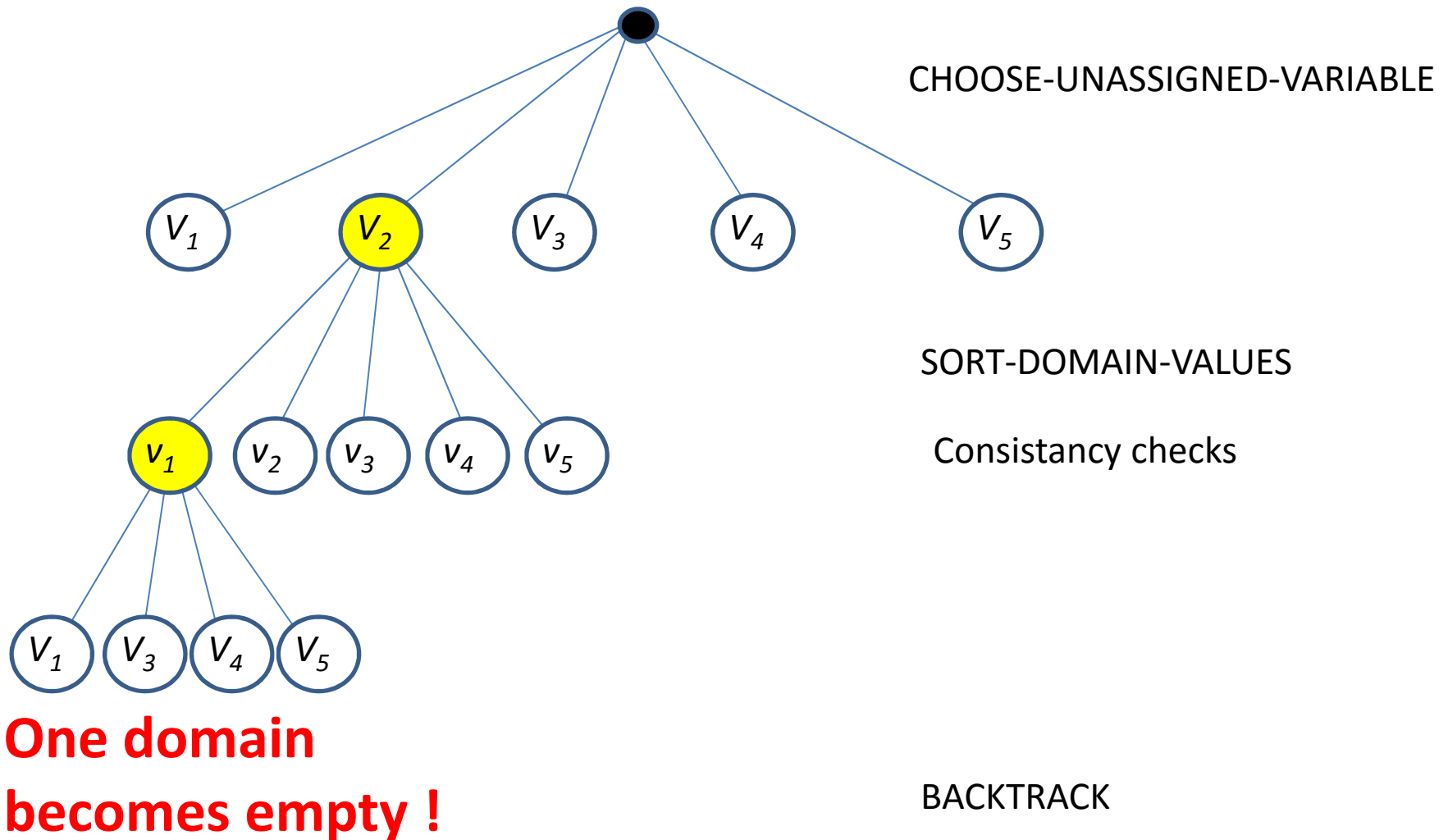
Algorithms : backtrack (5 / 14)



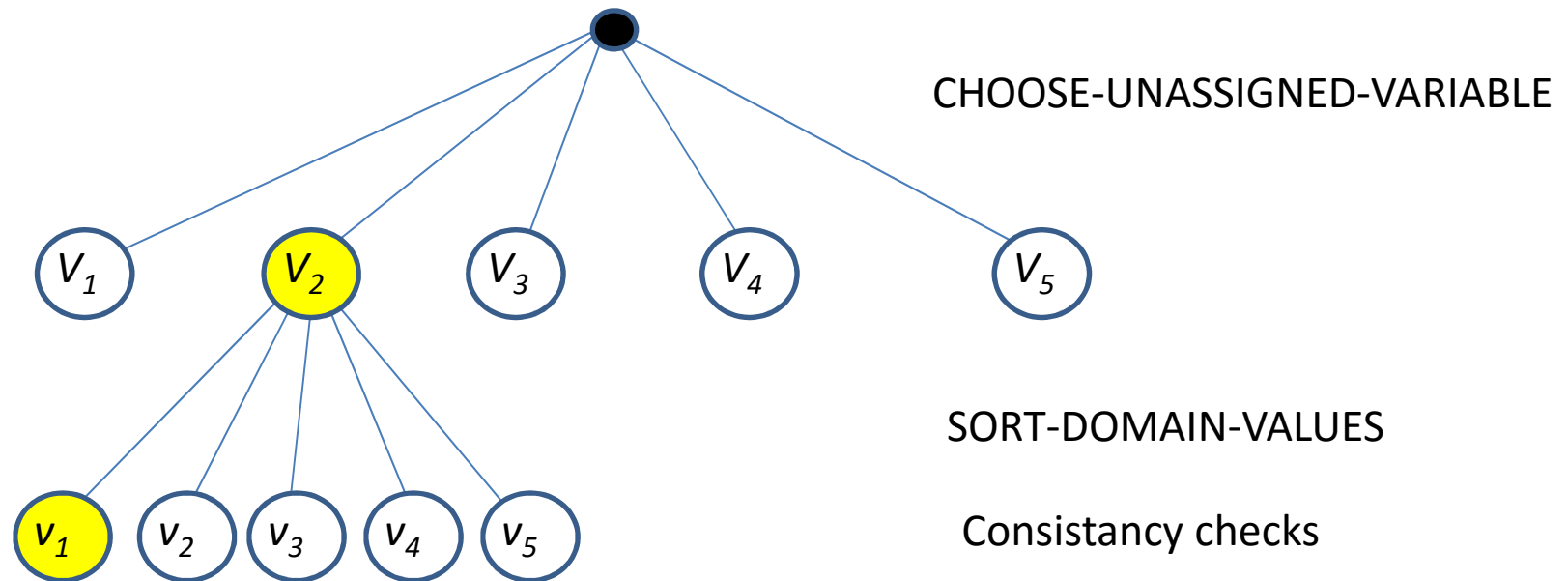
Algorithms : backtrack (6 / 14)



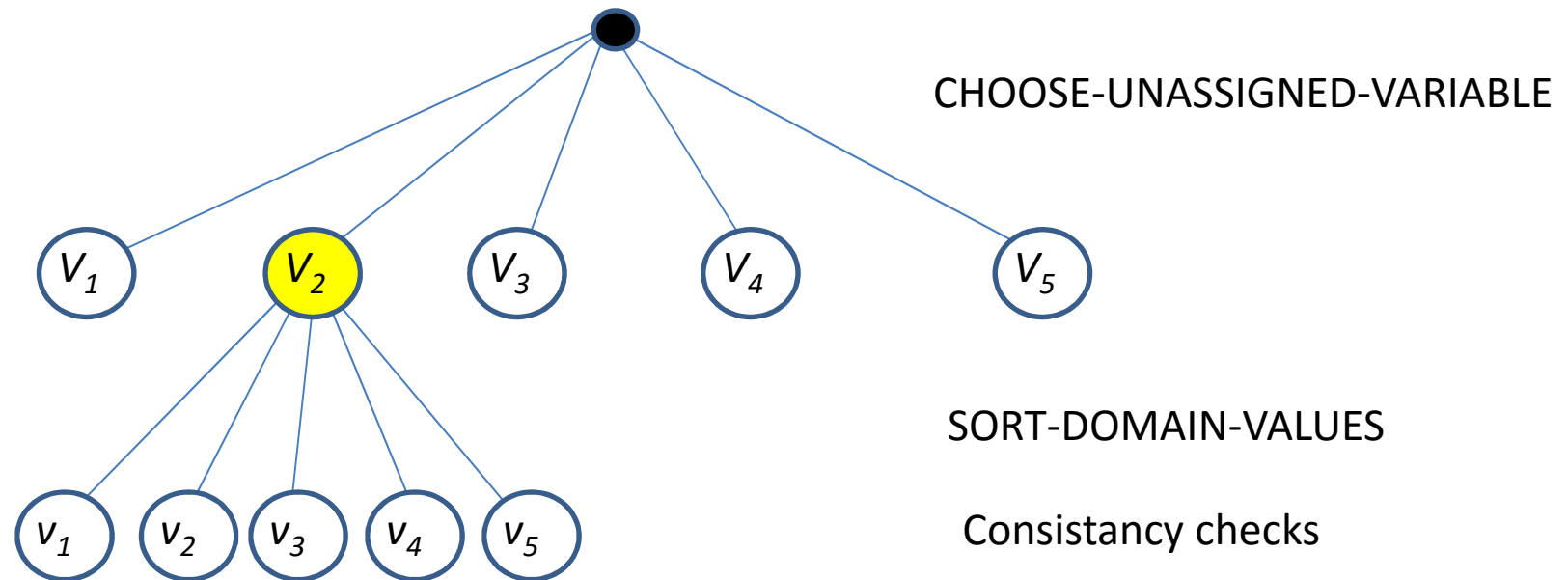
Algorithms : backtrack (7 / 14)



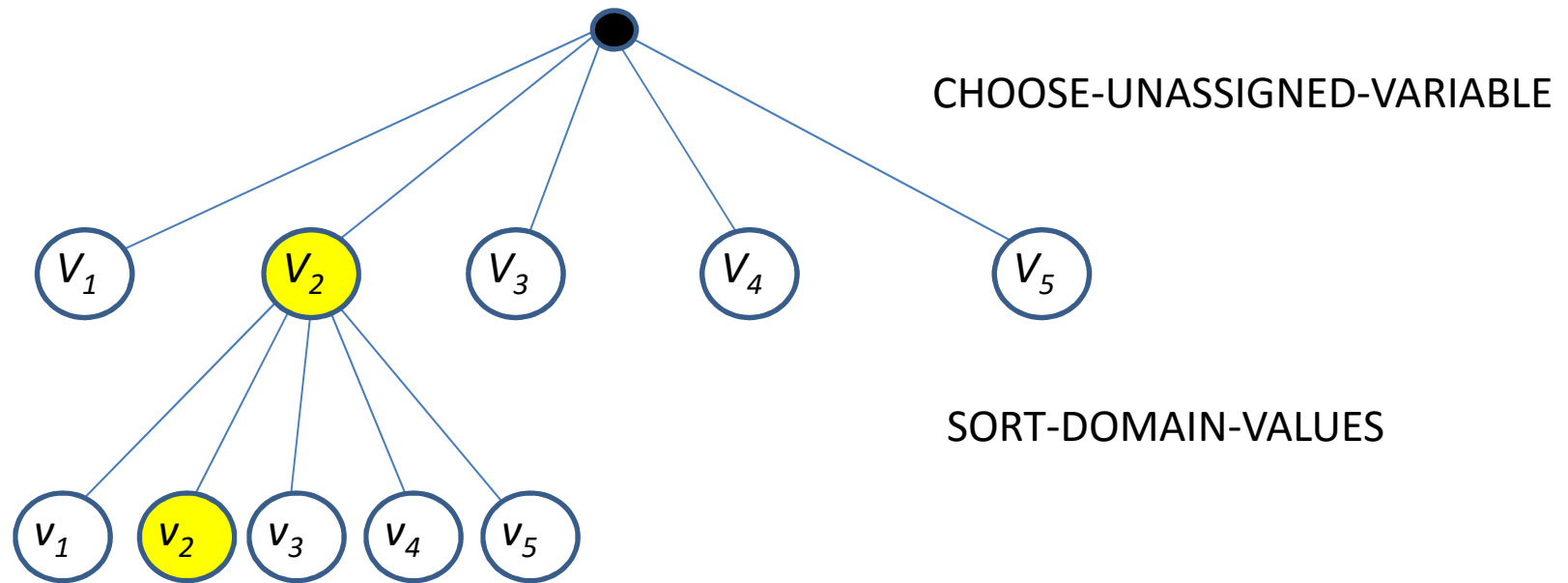
Algorithms : backtrack (8 / 14)



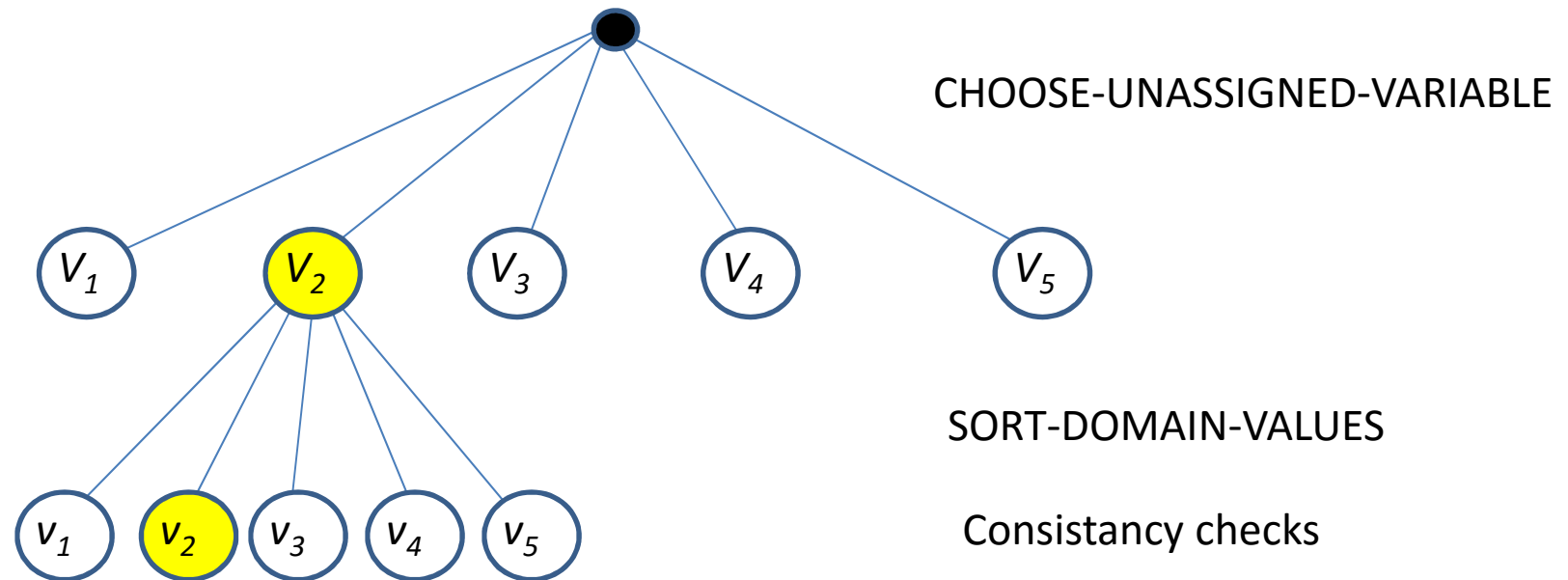
Algorithms : backtrack (9 / 14)



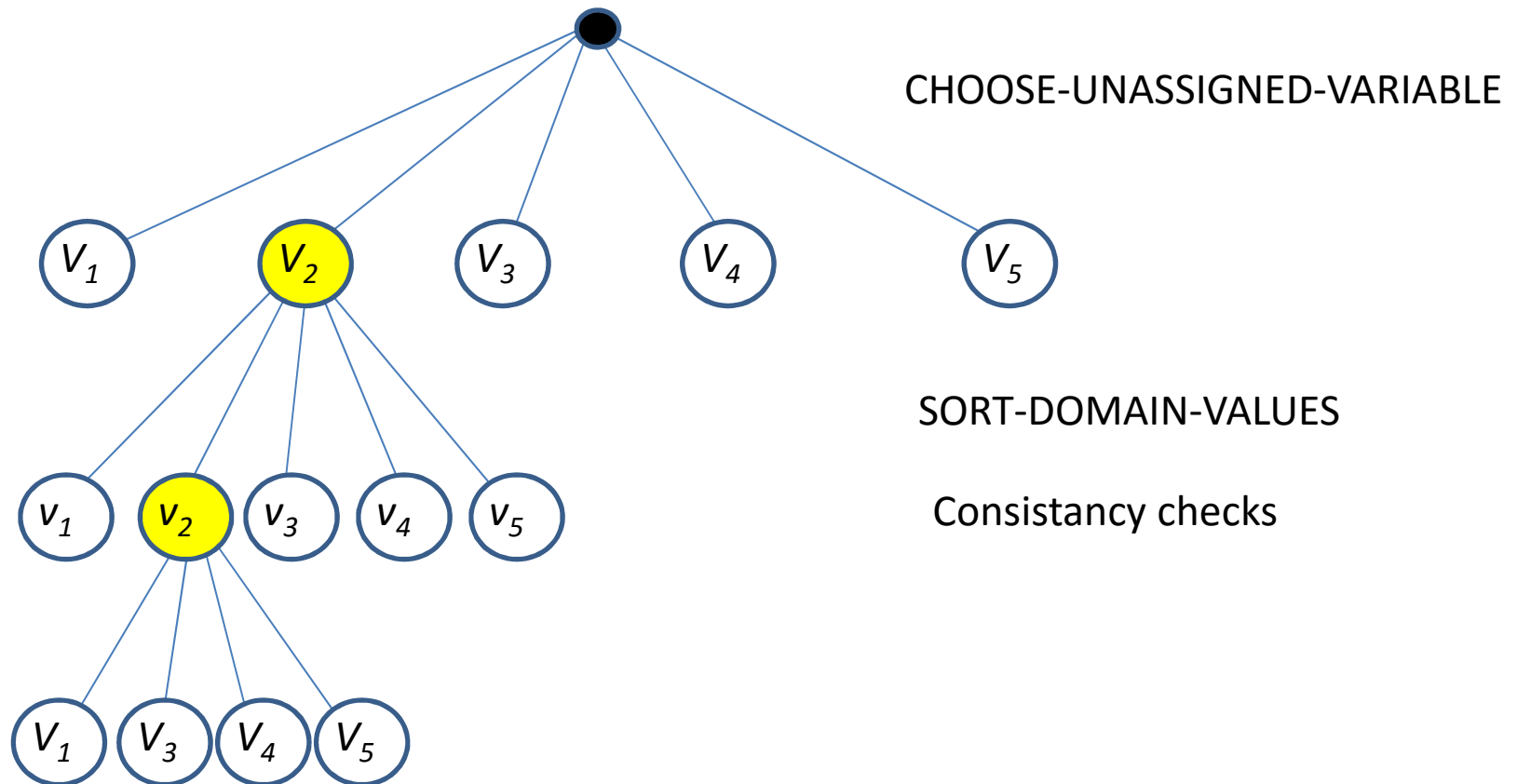
Algorithms : backtrack (10 / 14)



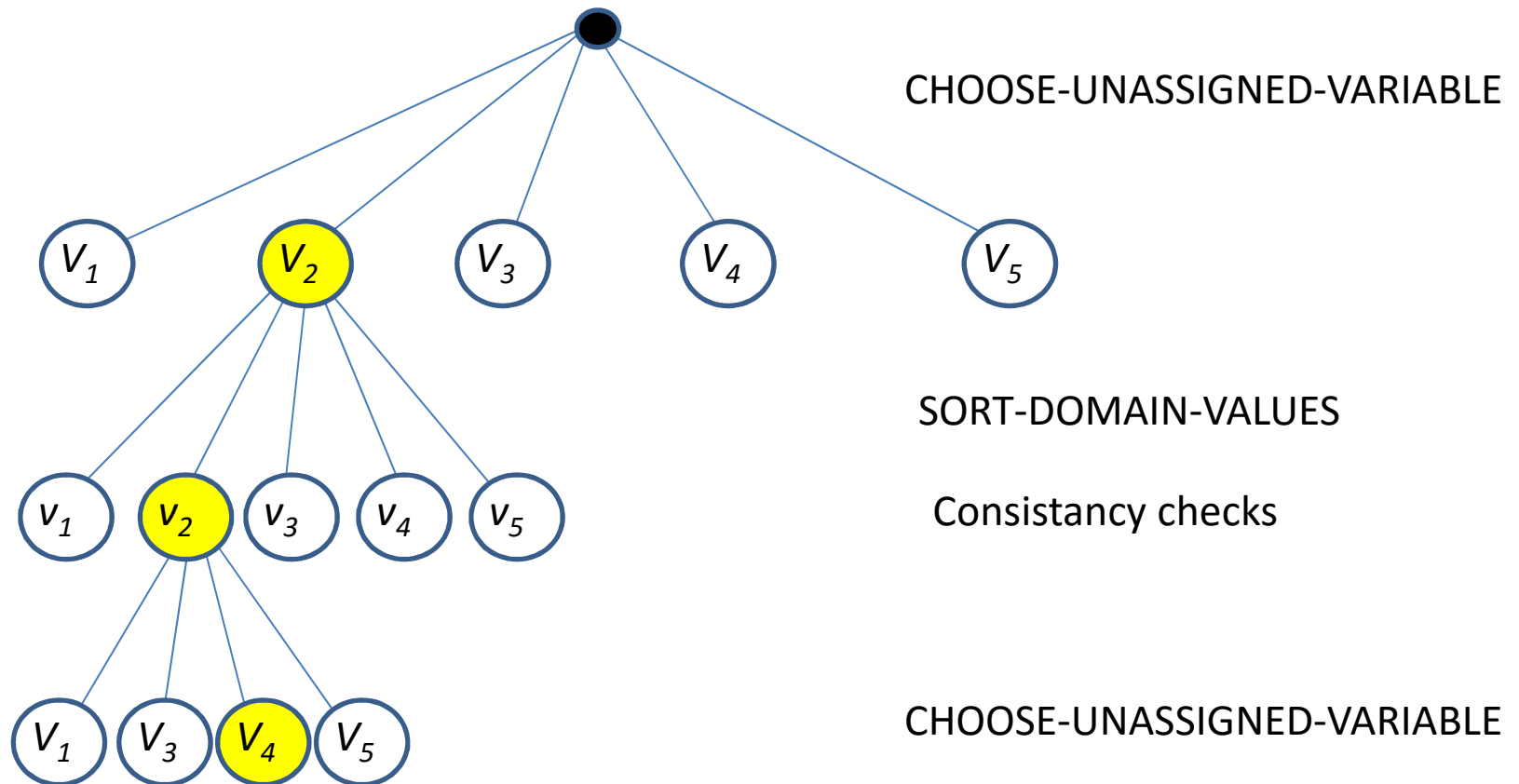
Algorithms : backtrack (11 / 14)



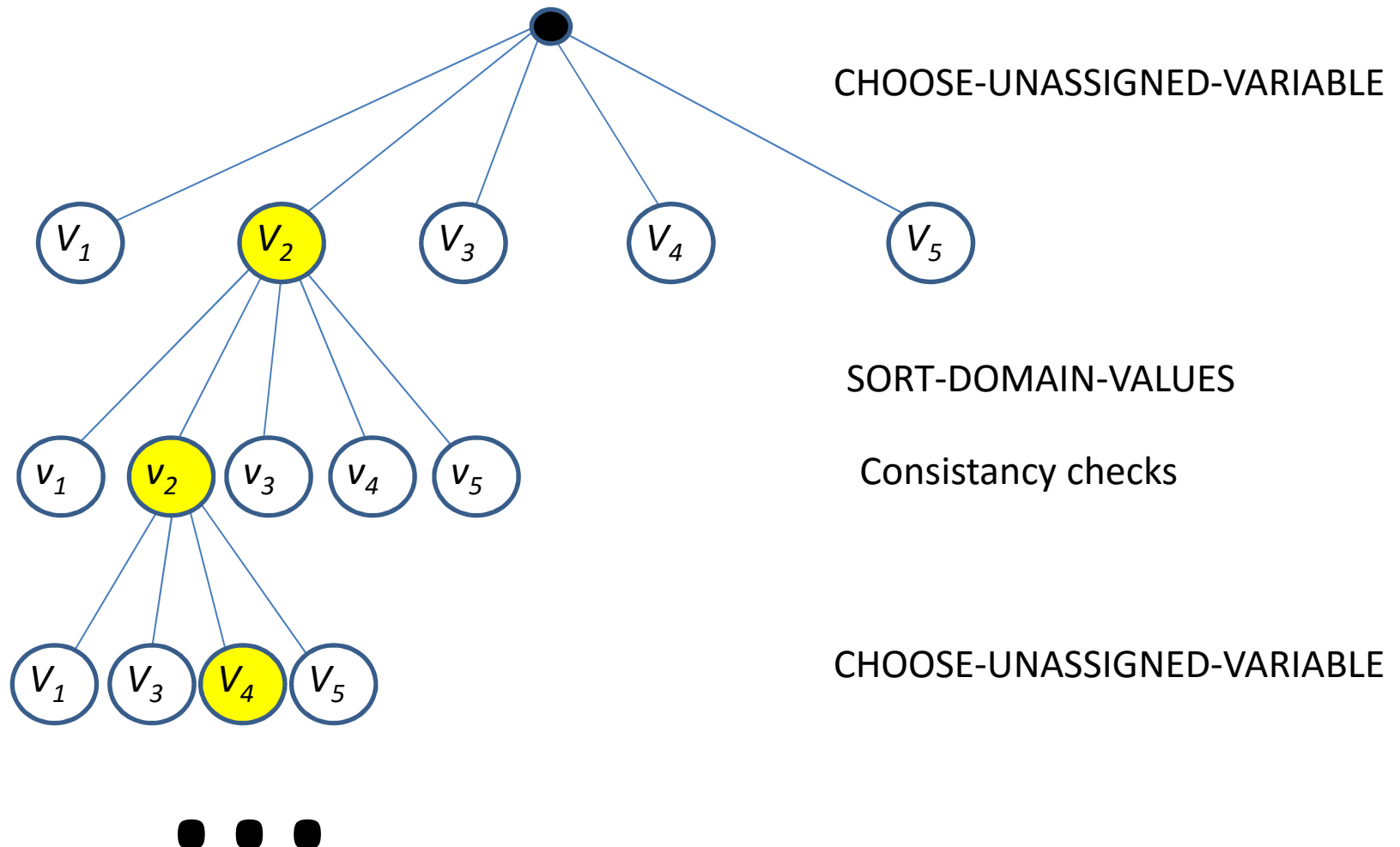
Algorithms : backtrack (12 / 14)



Algorithms : backtrack (13 / 14)



Algorithms : backtrack (14 / 14)



Heuristics (1 / 2)

- A heuristics can make a choice.
 - Expressed in terms of variables, domains and constraints.
 - Or can be based on exogeneous information (e.g., the application domain of the CSP).
 - Prototype in C++ : `int heuristics(Assignment* assignment, Csp* csp);`
- Heuristics on variables : CHOOSE-UNASSIGNED-VARIABLE()
 - Static / dynamic.
 - **First-fail** : choose the variable with the smallest domain.
 - **Smallest** : choose the variable with the smallest value in its domain.
 - **Constraint**: choose the variable linked to the maximum number of constraints.
 - ...

Heuristics (2 / 2)

- Heuristics on values : SORT-DOMAIN-VALUES()
 - Static / dynamic
 - **Min** : assign a variable to its minimum value
 - **Max** : assign a variable to its maximum value
 - **Median** : assign a variable to its median value; or different from its median value (middle-out)
 - **Split** : constrain the variable to its lower/upper half domain
 - **Regret** : assign the variable to the value which removes the least number of values to other variables.
 - ...
- Search strategy : additional constraints which orient search.

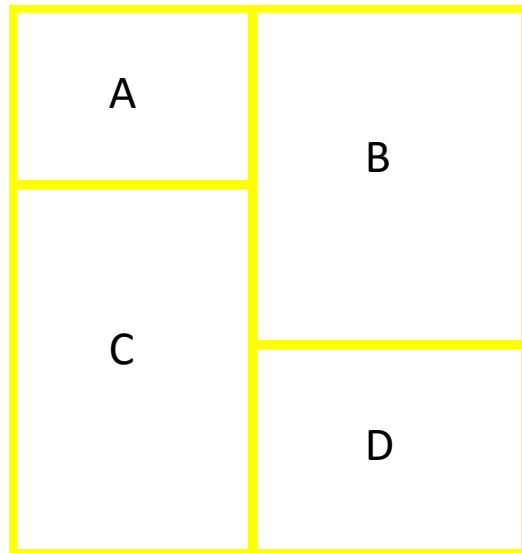
Filtering

- What does the assignment of a variable imply for other variables ?
- **FORWARD-CHECKING**: each time a variable V_i is instantiated, consider variables V_j connected to V_i by a constraint C_k , and remove from the domain of variable V_j the values which are inconsistent with constraint C_k .

Filtering by Forward-Checking

Graph coloring

Assign a color to A,B,C and D (below) so that no two colors are adjacent, with possible colors for each rectangle:

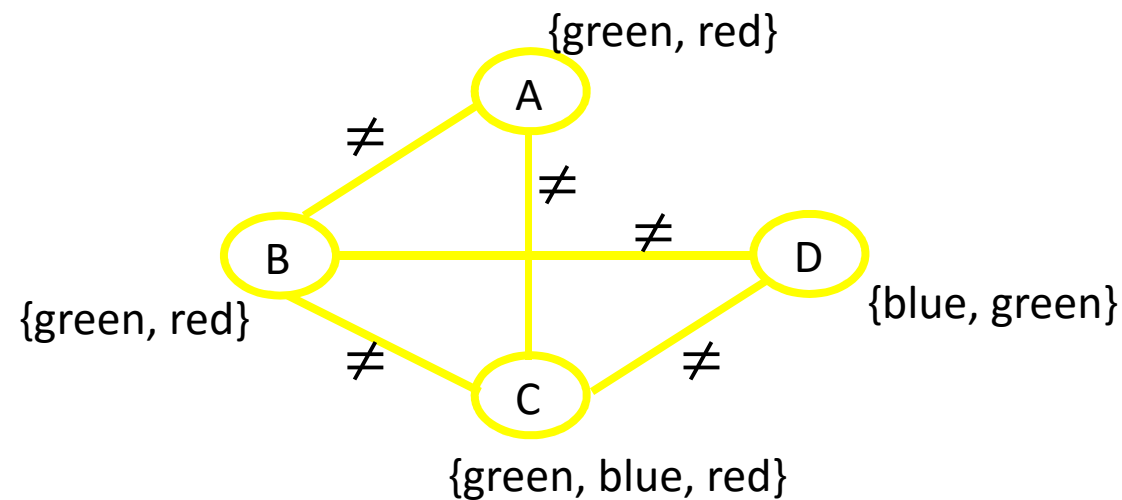


A and B are green or red

C is green, blue or red

D is blue or green

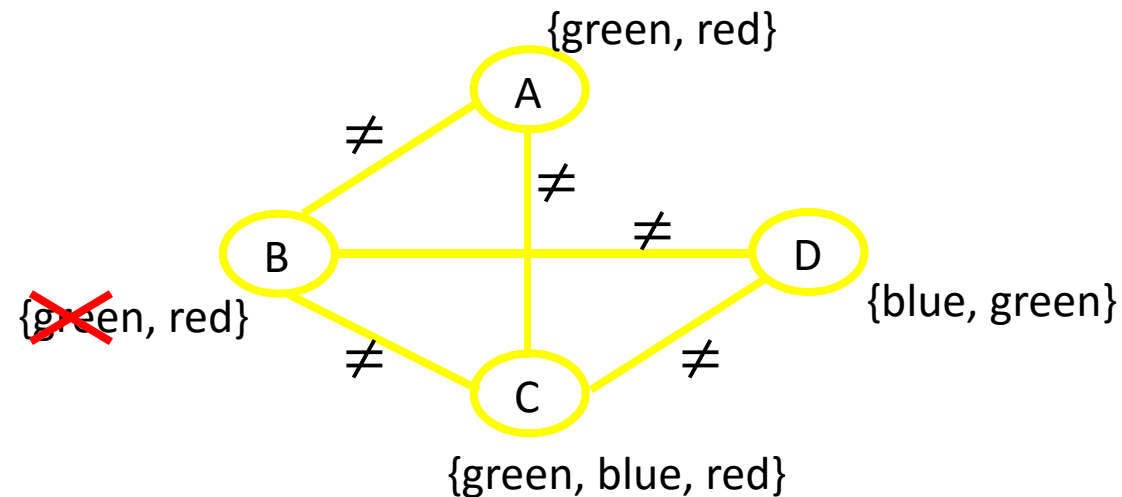
Filtering by Forward-Checking Model



- Some pairs of variables are linked by a constraint of difference
- The domain of each variable is shown in bracket {...}.

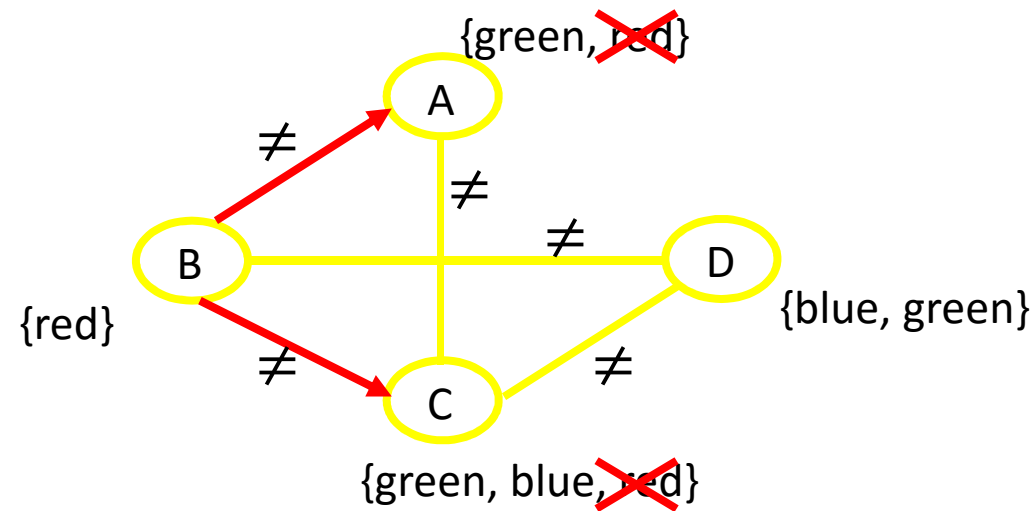
Filtering by Forward-Checking

- Let us assume B is arbitrarily assigned to red.



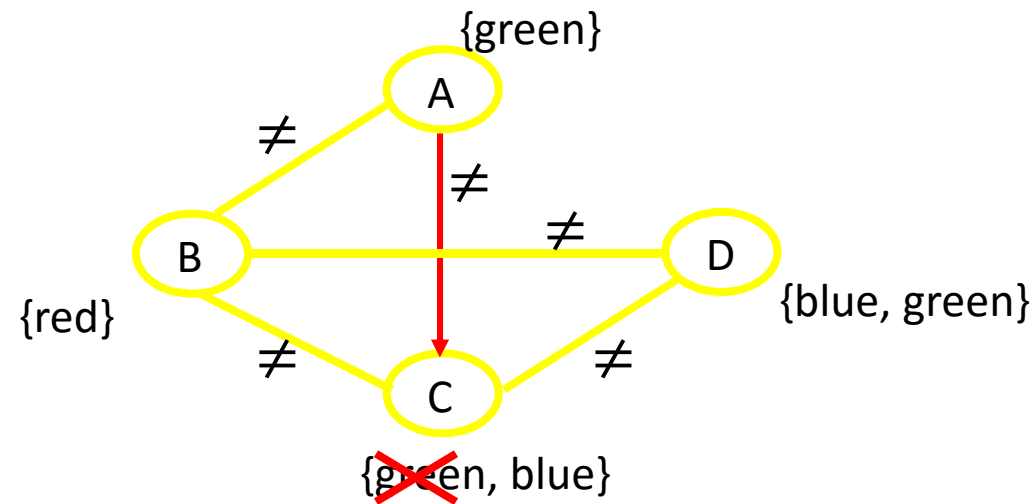
Filtering by Forward-Checking

- Instantiation of A to green.



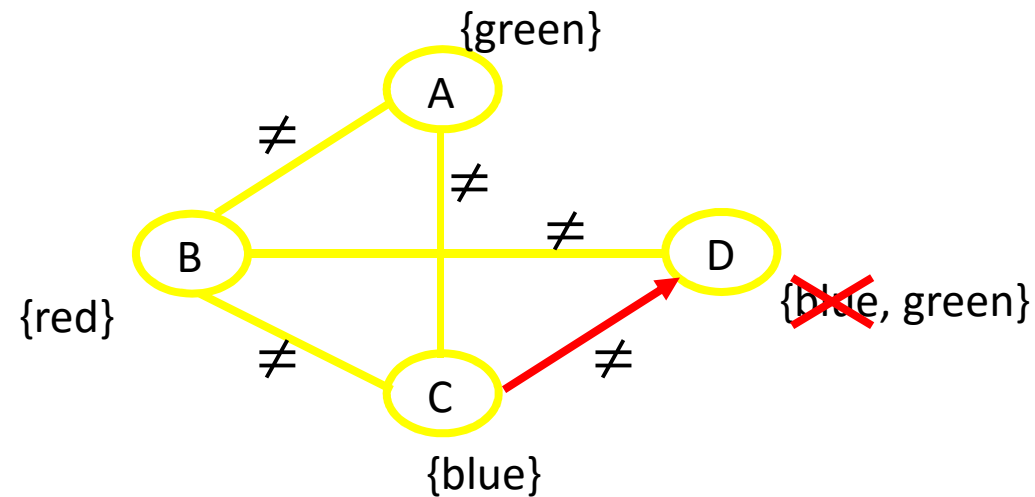
Filtering by Forward-Checking

- Instantiation of C to blue.



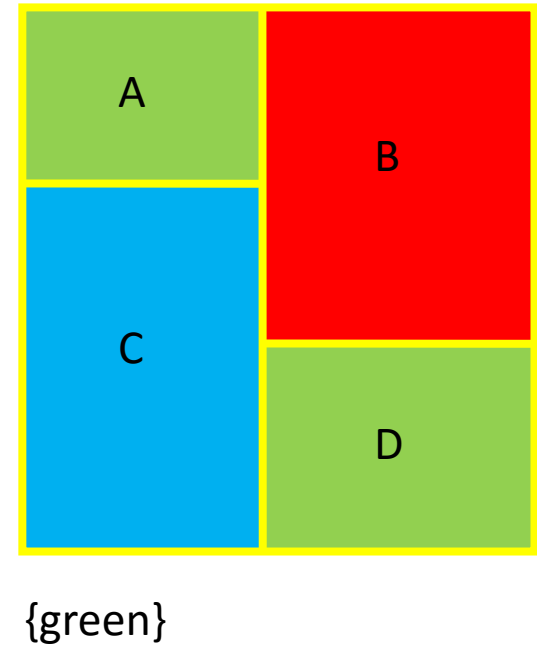
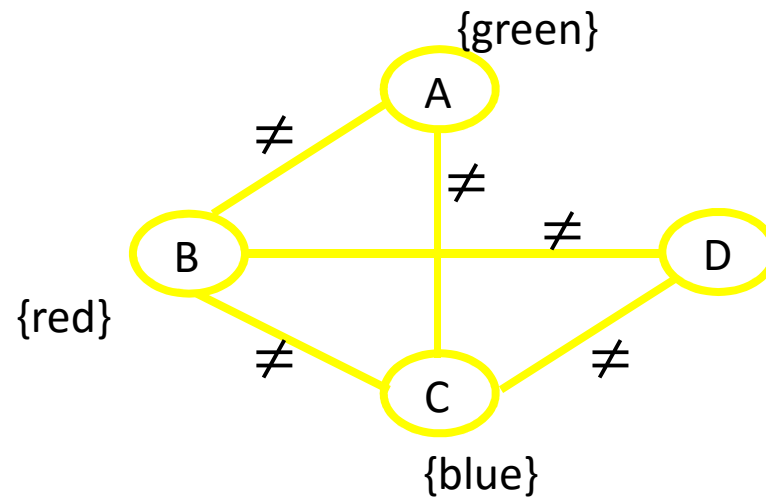
Filtering by Forward-Checking

- Instantiation of D to green.



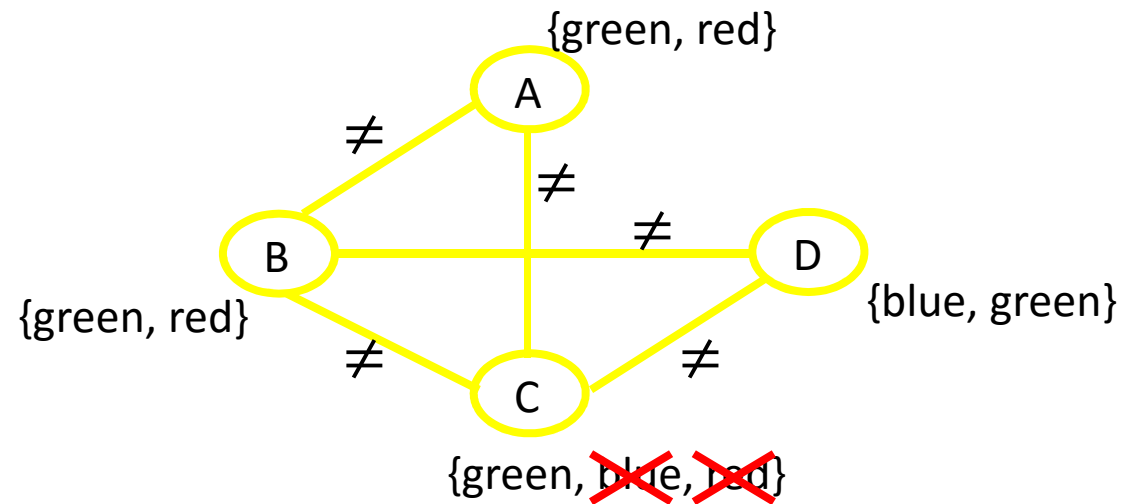
Filtering by Forward-Checking

- Solution !



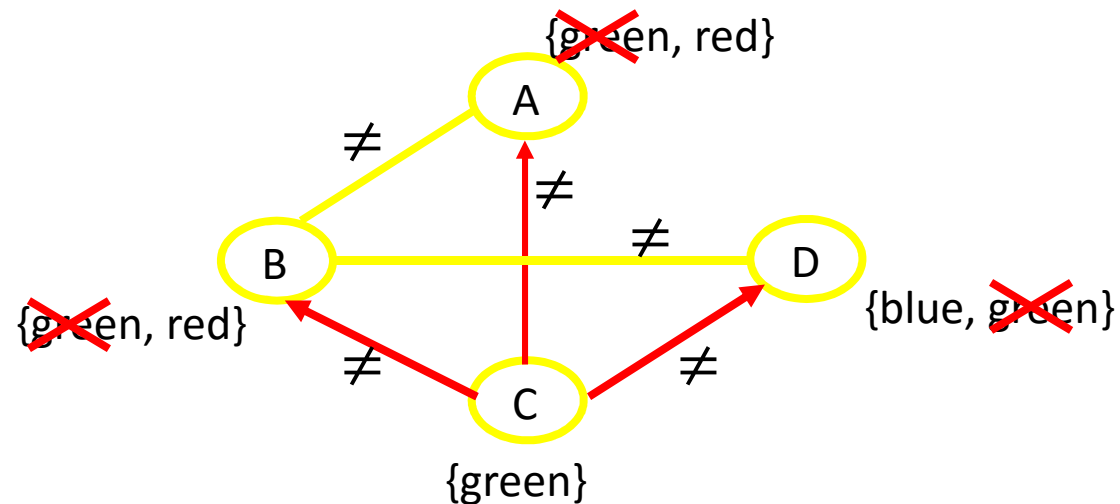
Filtering by Forward-Checking

- Now, let us assume that C is arbitrarily assigned to green.



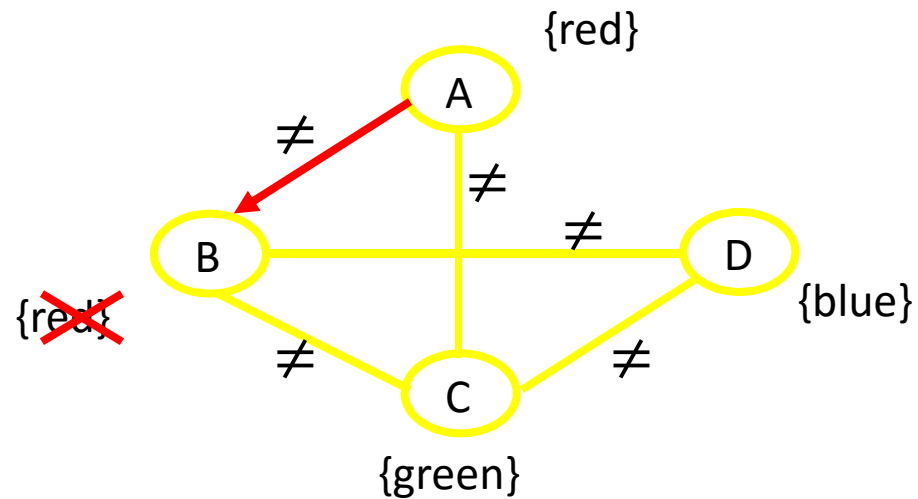
Filtering by Forward-Checking

- Instantiation of D to blue, and A and B to red.



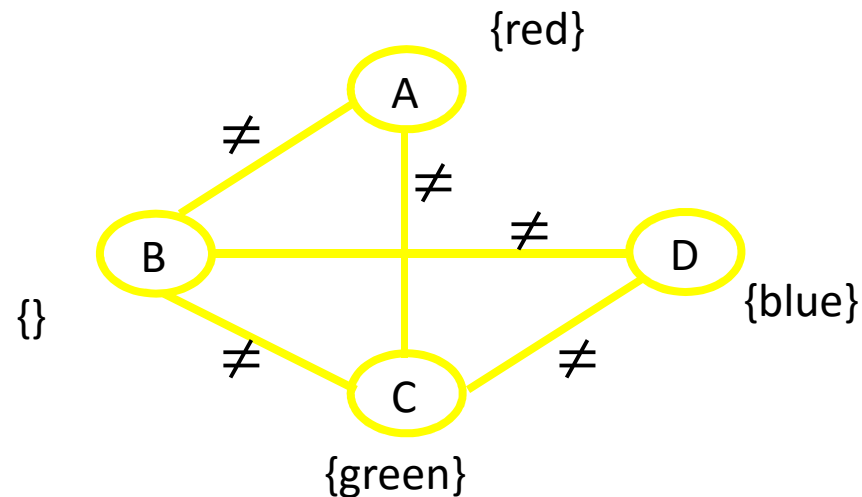
Filtering by Forward-Checking

- Removing red from B's domain.

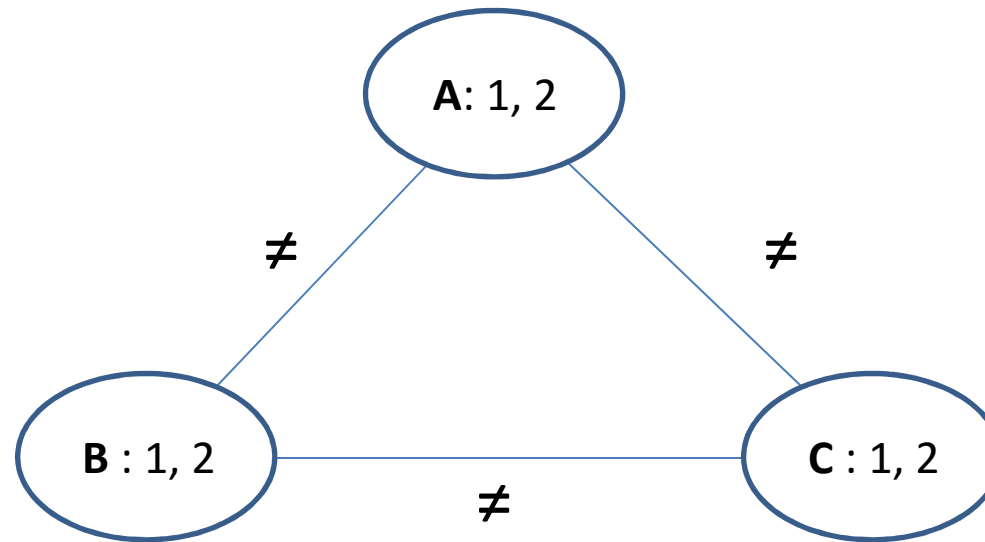


Filtering by Forward-Checking

- B has an empty domain: failure !
- Backtrack is needed in the process...



Arc consistency

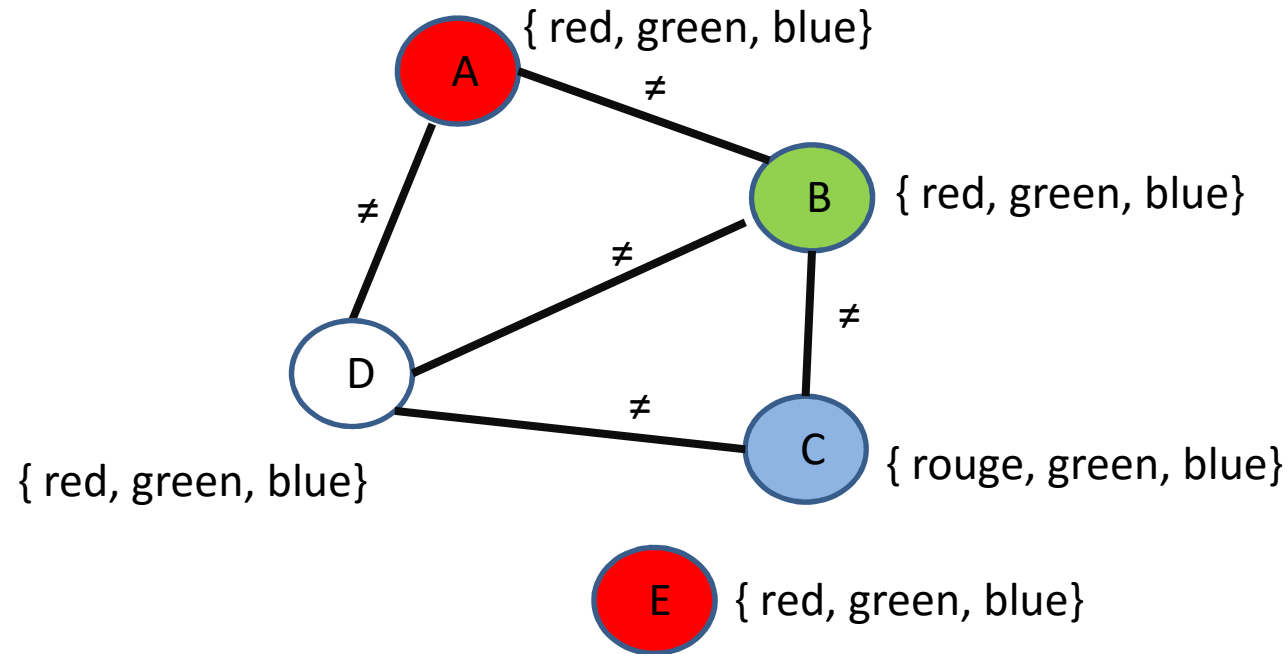


- Arc consistency is not sufficient for the example above: path consistency is required.
- K-consistency, strong k-consistency.

Back-jumping

- The algorithm Backtrack goes back to the previous choice (e.g., lastly assigned variable).
 - Chronological backtracking.
- Back-jumping: goes back to a variable which caused the failure (e.g., the most recent) in the search tree.
- The conflict set of a variable **V** is the set of previously instantiated variables, linked to **V** by a constraint.

Back-jumping



- Let us assume that the order of instantiation is **A**, **B**, **C**, **E**, **D**.
- **A** = red ; **B** = green ; **C** = blue ; **E** = red
- No value for **D**. Chronological backtracking goes back to **E** !!!
- The conflict set of **D** is { **A**, **B**, **C** }. Back-jumping goes back to **C** and not **E**.

Conclusion

- Constraint programming is a paradigm for solving combinatorial problems.
- Constraint programming is based on a model (variables, domains, constraints) and an algorithm.
- The algorithm uses forward checking to filter the domains of variables (removing values). Arc consistency is the more general algorithm for that.
- When an empty domain is detected, goes up in the search tree (chronological backtracking, back jumping) to change a previously made choice (and do better!).